

SN: _____, Name: _____

ABSOLUTELY NO CHEATING!

Note: This is a close-book examine. You can use pencil or any pen in answering the problems. Dictionary and Calculators are NOT allowed.

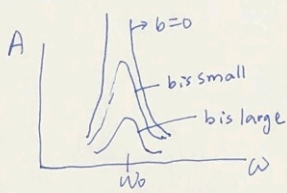
Problems (6 Problems, total 100%) The final examines will take place with two one-hr examines each is 50% of the final grades.

1. **Forced oscillation: (20%)** In a forced oscillation, if you applied a force $F_0 \sin \omega t$ to the oscillation, where the displacement of the oscillation can be represented as $x(t) = A \cos(\omega t + \phi)$, after applied the force, the amplitude A can be calculated as $A = \frac{F_0/m}{\sqrt{(\omega^2 - \omega_0^2)^2 + (\frac{b\omega}{m})^2}}$. (a) Draw the amplitude as function of the applied frequency ω is near the natural frequency and when the damping is very large, small and $b=0$. (b) Briefly explain your answer in (a).

1. (a) $x = A \cos(\omega t + \phi)$

$$A = \frac{F_0/m}{\sqrt{(\omega^2 - \omega_0^2)^2 + (\frac{b\omega}{m})^2}}$$

When the applied oscillation is near ω_0 .
depending on the value of the damping term b .
there are 3 possibilities. $b = \text{small}$, $b = \text{large}$, $b = 0$



(b) When ω is near the natural frequency ω_0 , the amplitude depends on the damping term $(\frac{b\omega}{m})^2$.

$$A = \frac{F_0/m}{(\frac{b\omega}{m})} = \frac{F_0}{m} \frac{m}{b\omega} = \frac{F_0}{b\omega}$$

- ① When $b = \text{small}$, A is large
- ② When $b = 0$, $A \rightarrow \infty$
- ③ When $b = \text{large}$, A is small

2. **Thermal expansion: (15%)** A material is known to have the coefficient of linear expansion α at certain temperature change ΔT , prove that the volume coefficient of expansion $\beta = 3\alpha$.

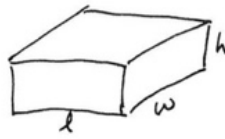
— Linear Expansion

$$\Delta L = L \alpha \Delta T$$

$\alpha \equiv$ Coefficient of linear expansion
[$1/\text{deg}$, $1/K$]

— Volume expansion

$$\Delta V = V \beta \Delta T \quad \beta = 3\alpha$$



at T_i : $V_i \equiv lwh$

$$T \rightarrow T_i + \Delta T$$

$$V \rightarrow V_i + \Delta V$$

$$\begin{aligned} V_i + \Delta V &= (l + \Delta l)(w + \Delta w)(h + \Delta h) \\ &= (l + \alpha l \Delta T)(w + \alpha w \Delta T)(h + \alpha h \Delta T) \\ &= lwh (1 + \alpha \Delta T)^3 \\ &= V_i [1 + 3\alpha \Delta T + 3(\alpha \Delta T)^2 + (\alpha \Delta T)^3] \end{aligned}$$

$$\therefore \frac{\Delta V}{V_i} = 3\alpha \Delta T + 3(\alpha \Delta T)^2 + (\alpha \Delta T)^3$$

neglect higher order terms

$$\frac{\Delta V}{V_i} = 3\alpha \Delta T$$

$$\therefore \beta = 3\alpha$$

3. **Doppler Effect:** (10%) In a general case, the frequency shift caused by the relative motion of the sound source and sound detector is described by Doppler Effect. Let f be the original sound frequency, and f' is the detected frequency due to relative motion. The speed of the sound is V and the speed of the detector is V_D , the speed of the source is V_s . In general, the detected frequency can be expressed

as $f' = f \frac{V \pm V_D}{V \mp V_s}$. If we define the relative velocity of the wave source and the

detector as $u = V_s \pm V_D$. Show that this expression can also be reduced to

$$f' = f \left(1 \pm \frac{u}{V} \right)$$

$$\begin{aligned}
 f' &= f \frac{V \pm V_D}{V \mp V_s} = f (V \pm V_D) (V \mp V_s)^{-1} \\
 &= f \left(1 \pm \frac{V_D}{V} \right) \left(1 \mp \frac{V_s}{V} \right)^{-1} \\
 &= f \left[1 \pm \frac{V_D}{V} + \dots \right] \left[1 \pm \frac{V_s}{V} + \dots \right] \quad u = V_s \pm V_D \\
 &= f \left(1 \pm \frac{V_s}{V} \pm \frac{V_D}{V} + \frac{V_s V_D}{V^2} + \dots \right) \\
 &= f \left(1 \pm \frac{V_s \pm V_D}{V} + \dots \right) \quad \therefore \underline{f' = f \left(1 \pm \frac{u}{V} \right)}
 \end{aligned}$$

4. **Simple Harmonic Oscillator:** (10%) Take a spring of force constant k , with a mass m attached to the end. This oscillator is allowed to oscillate freely with maximum amplitude A . Prove that the total energy of a simple harmonic oscillator is constant. (b) **Simple harmonic Oscillation:** A spring mass oscillator has a total energy E_0 and an amplitude of x_0 . Let the spring constant is k . (a) How large will the kinetic energy (E_k) and potential energy (E_p) be for it when $x=x_0/2$? (b) For what value of x will $E_k = E_p$?

Let $x(t) = A(\cos \omega t + \phi)$ represents a SHO's Amplitude

$$\text{Then } v = \frac{dx(t)}{dt} = -\omega A \sin(\omega t + \phi)$$

Total energy of a SHO $E_{\text{tot}} = E_k + E_p$

$$E_k = \frac{1}{2} m v^2 = \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t + \phi)$$

$$E_p = \frac{1}{2} k x^2 = \frac{1}{2} k A^2 \cos^2(\omega t + \phi)$$

$$E_{\text{total}} = \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t + \phi) + \frac{1}{2} k A^2 \cos^2(\omega t + \phi)$$

$$= \frac{1}{2} k A^2 = \text{Constant.}$$

E_{total} determined by k and Max. Amplitude A

4-2

4. The total energy is $E_0 = E_k + E_p$

$$\text{or, } \frac{1}{2} k x_0^2 = \frac{1}{2} k x^2 + E_k \quad \text{Let the Spring Constant be } k$$

$$\begin{aligned} \text{(a) When } x = \frac{1}{2} x_0, E_p &= \frac{1}{2} k \left(\frac{1}{2} x_0\right)^2 \\ &= \frac{1}{4} E_0 \end{aligned}$$

$$\begin{aligned} E_k &= E_0 - E_p \\ &= \frac{1}{2} k x_0^2 - \frac{1}{4} E_0 \\ &= E_0 - \frac{1}{4} E_0 \\ &= \frac{3}{4} E_0 \end{aligned}$$

$$\begin{aligned} \text{(b) If } E_p &= E_k \text{ @ } E_p = \frac{1}{2} E_0 \\ &= \frac{1}{2} \cdot \frac{1}{2} k x_0^2 \\ &= \frac{1}{4} k x_0^2 \\ &= \frac{1}{2} k x^2 \end{aligned}$$

$$\therefore x = \frac{x_0}{\sqrt{2}}$$

5.

Solution: (*Set-up from the basic*)

$$(a) \quad F = \frac{GmM_{ins}}{R}$$

$$M_{ins} = \rho V_{ins} = \rho \frac{\pi R^2}{4} \quad \therefore \quad V_{ins} = \frac{\pi R^2}{4}$$

$$So \quad F = \frac{\pi Gm\rho}{4} R = kR \quad \therefore \quad k = \frac{\pi Gm\rho}{4}$$

$$F = -kx$$

$$T = \frac{2\pi}{f} = \frac{2\pi}{\pi} \sqrt{\frac{m}{k}} = \frac{2\pi}{\pi} \sqrt{\frac{m}{\frac{\pi Gm\rho}{4}}} = \sqrt{\frac{4}{\pi G\rho}}$$

$$f = \pi \sqrt{\frac{k}{m}}$$

$$T = \frac{2\pi}{f} = \frac{2\pi}{\pi} \sqrt{\frac{m}{k}} = \frac{2\pi}{\pi} \sqrt{\frac{m}{\frac{\pi Gm\rho}{4}}} = \sqrt{\frac{4}{\pi G\rho}}$$

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6.

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$$\psi = A \cos(kx - \omega t)$$

$$\psi = A \cos(kx + \omega t)$$

$$\psi = b \cos(kx - \omega t)$$

$$\psi = y.$$

$$\psi = A \cos(kx - \omega t) + A \cos(kx + \omega t)$$

$$\psi = A \cos(kx - \omega t) + A \cos(kx + \omega t)$$

$$\psi = A \cos(kx - \omega t) + A \cos(kx + \omega t) = C + D = \frac{C+D}{2} + \frac{D-C}{2}$$

$$\psi = A \cos(kx - \omega t) + A \cos(kx + \omega t)$$

$$\psi = A \cos(kx - \omega t) + A \cos(kx + \omega t)$$

$$\frac{\psi}{A} = \cos(kx - \omega t) + \cos(kx + \omega t) = 2 \cos(kx) \cos(\omega t)$$

$$\psi = A \cos(kx) \cos(\omega t)$$
