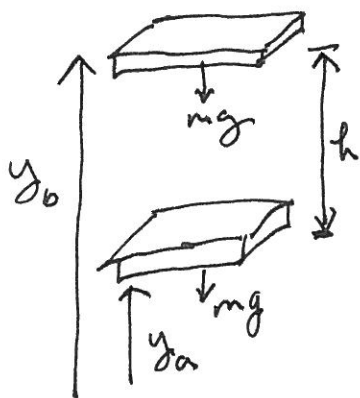


Chap 8 Potential energy Conservation of Energy

PS-1



The book Subject to the same gravitational force mg

The work done by the gravity is

$$mg y_b - mg y_a = mgh$$

\downarrow
This much energy has the potential to become ~~an~~ kinetic energy

$$mgh \rightarrow \frac{1}{2} m v^2$$

Gravitational potential energy

$$W = (F_{app}) \cdot \Delta r$$

$$= (mg \hat{j}) \cdot [(y_b - y_a) \hat{j}]$$

$$= mg y_b - mg y_a$$

$$(7-14) \quad \sum W = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$= (mg y_f - mg y_i)$$

It is similar to the energy transferred to kinetic energy

$$\therefore U \equiv mg y$$

$$W = \Delta U_g$$

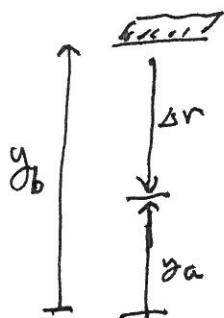
→ The gravitational potential energy depends on only the vertical height of the system.

$$W = (F_{app}) \cdot \Delta r = (mg \hat{j}) \cdot [(x_b - x_a) \hat{i} + (y_b - y_a) \hat{j}]$$

$$= mg y_b - y_a$$

note: $\hat{j} \cdot \hat{i} = 0$ orthogonal

8.2 The isolated system - Conservation of Mechanical energy



If the book falls back to its origin

$$\begin{aligned}
 W_{\text{on book}} &= (mg) \cdot \Delta r \\
 &= (-mg\hat{j}) \cdot [(y_b - y_a)\hat{j}] \\
 &= mgy_b - mgy_a \\
 &= \Delta E_k \\
 &= \Delta K_{\text{book}}
 \end{aligned}$$

$$\begin{aligned}
 mgy_b - mgy_a &= -(mgy_a - mgy_b) \\
 &= -(U_f - U_i) \\
 &= -\Delta U_g
 \end{aligned}$$

$$\therefore \Delta K = -\Delta U_g$$

$$\Delta K + \Delta U_g = 0$$

$$\begin{aligned}
 \text{Mechanical energy } \bar{E}_{\text{mech}} &\equiv K + U_g \\
 &= K + U
 \end{aligned}$$

$$\Delta K + \Delta U = (K_f - K_i) + (U_f - U_i) = 0$$

$$\rightarrow K_f + U_f = K_i + U_i$$

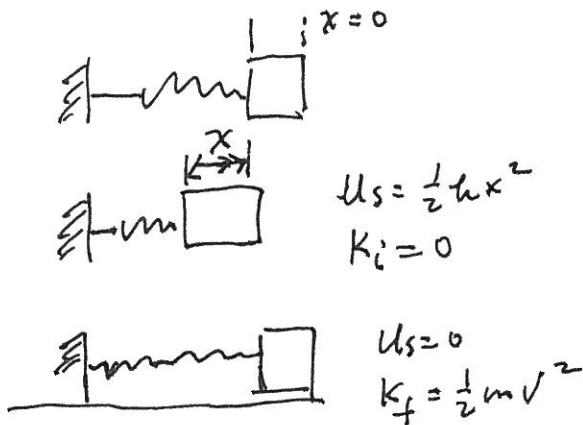
$$\frac{1}{2}mv_f^2 + mgy_f = \frac{1}{2}mv_i^2 + mgy_i$$

— Conservation of energy

Elastic potential energy

$$W_{\text{App}} = \frac{1}{2} k x_f^2 - \frac{1}{2} k x_i^2$$

$\therefore U_s \equiv \frac{1}{2} k x^2$ - The energy stored in the deformed spring



Conservative force

- 1) The work done is independent of the path taken
- 2) The work done through a closed path is zero

Non Conservative force

Acting within a system cause a change

$$\Delta K = -f_k d \quad \text{— the decrease in kinetic energy due to a non conservative force}$$

$$\Delta \bar{E}_{\text{mech}} = \Delta K + \Delta U_g = -f_k d$$

The work done by a conservative force W_c

$$W_c = \int_{x_i}^{x_f} F_x dx = -\Delta U$$

But $\Delta U = U_f - U_i = - \int_{x_i}^{x_f} F_x dx$

$$U_f = - \int_{x_i}^{x_f} F_x dx + U_i$$

we ~~only~~ often take it as zero
zero point of the potential



$$dU = -F_x dx$$

$$F_x = -\frac{dU}{dx}$$

The negative derivative of the potential energy of the system is the force.

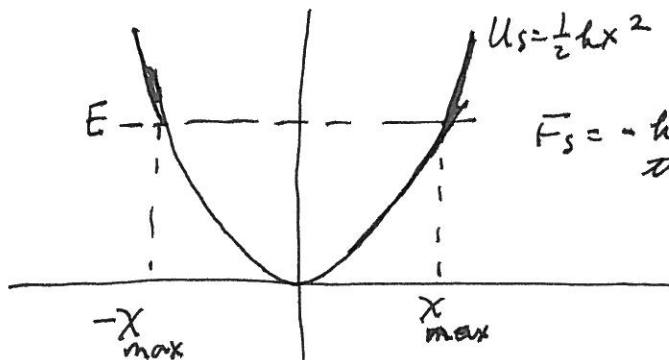
for example $F_s = -kx$

$$U_s = \frac{1}{2} kx^2$$

Do example 8.11 (page 237)

$$-\frac{dU_s}{dx} = -\frac{d}{dx} \left(\frac{1}{2} kx^2 \right) = -kx$$

plot U_s



$F_s = -kx =$ the slope of the U_s

U_s is maximum for unstable equilibrium

neutral equilibrium

stable equilibrium

Chap 8. Conservation of energy -2 -①

Energy is always conserved.

in an nonisolated system ; $\Delta E_{\text{system}} = \sum T$

$T =$ energy transferred to the environment.

$$\rightarrow \Delta K + \Delta U + \Delta E_{\text{int}} = W + Q + T_{\text{MW}} + \dots$$

all items on each side can be zero

Isolated system : No energy transferred across the boundary of the system.

$$\Delta K = -\Delta U_g \rightarrow \text{in a book system}$$

$$W_{\text{on book}} = (m\vec{g}) \cdot \Delta\vec{r} = (-mg\hat{j}) \cdot [(y_f - y_i)\hat{j}]$$

$$= mgy_i - mgy_f$$

$$= \Delta K_{\text{on book}}$$

$$= -(mgy_f - mgy_i)$$

$$= -\Delta U_g$$

$$\therefore \Delta K = -\Delta U_g$$

$$\rightarrow \Delta K + \Delta U_g = 0$$

$$= \Delta E_{\text{mech}}$$

$$\rightarrow \Delta E_{\text{mech}} = 0$$

Kinetic friction, check Fig 8.7. page 204

$$\sum W_{\text{other force}} = \int (\sum \vec{F}_{\text{other force}}) \cdot d\vec{r}$$

page 205

$$\sum W_{\text{other force}} + \int \vec{f}_k \cdot d\vec{r} = \int m \vec{a} \cdot d\vec{r} = \int m \frac{d\vec{v}}{dt} \cdot d\vec{r}$$

↑
friction

$$= \int_{t_i}^{t_f} m \left(\frac{d\vec{v}}{dt} \cdot \vec{v} \right) dt$$

Note: $\frac{d}{dt} (\vec{v} \cdot \vec{v}) = \frac{d\vec{v}}{dt} \cdot \vec{v} + \vec{v} \cdot \frac{d\vec{v}}{dt} = 2 \frac{d\vec{v}}{dt} \cdot \vec{v}$

$$\therefore \frac{d\vec{v}}{dt} \cdot \vec{v} = \frac{1}{2} \frac{d}{dt} (\vec{v} \cdot \vec{v}) = \frac{1}{2} \frac{dv^2}{dt}$$

$$\begin{aligned} \therefore \sum W_{\text{other force}} + \int \vec{f}_k \cdot d\vec{r} &= \int_{t_i}^{t_f} m \cdot \left(\frac{1}{2} \frac{dv^2}{dt} \right) dt \\ &= \frac{1}{2} m \int_{v_i}^{v_f} d(v^2) = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \Delta K \end{aligned}$$

$$\begin{aligned} \sum W_{\text{other}} + \int \vec{f}_k \cdot d\vec{r} &= \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \Delta K \\ &\quad \underbrace{\qquad\qquad\qquad}_{= -f_k dr} \end{aligned}$$

$$\sum W_{\text{other}} - f_k d = \Delta K$$